

Solution Orbit for k and epsilon Model for Turbulent Flow in Porous Media

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Turbulent flow within porous media such as fault rocks can affect dynamic earthquake rupture processes and has attracted interests of many researchers. Among models treating the turbulent flow, the k-epsilon model has widely been employed, where k is the turbulent kinetic energy and epsilon is the dissipation rate of k. However, analytical treatment associated with the effect of the initial values of k and epsilon on the final state has not been performed.

We assume a one-dimensional homogeneous porous medium and isotropic turbulence. We also assume that the density of the fluid, ρ , and the porosity, ϕ , are constant, and the ensemble averages of ϕk and $\phi \epsilon$ will be written as k and ϵ below, respectively. With these assumptions, it should be emphasized that exactly the same straight line given by the equation $\epsilon = c_k u_D k / \sqrt{K}$ is a nullcline common to both variables on the k-epsilon phase space, where c_k is a constant number, u_D is averaged Darcy velocity, and K is permeability. We can regard this line as a line attractor or repeller as observed in other systems such as Suzuki (2017). Moreover, the straight line $\epsilon = 0$ (k axis) is also a nullcline for epsilon.

Actually, the analytical form of solution orbits is given by $\epsilon = \epsilon_0 (k/k_0)^{C_2}$, where C_2 is a constant, 1.9. Using this, we show below that the common nullcline $\epsilon = c_k \phi u_D k / \sqrt{K}$ is a line attractor for this solution orbit. First, we define Region I as the region $0 < \epsilon < c_k \phi u_D k / \sqrt{K}$ on the phase space, and Region II as the region $\epsilon > c_k \phi u_D k / \sqrt{K} > 0$. We also define the point (k_f, ϵ_f) as the point where the solution orbit passing the point (k_0, ϵ_0) crosses the nullcline. With these definitions, we have relations $k_0 < k_f$ and $\epsilon_0 < \epsilon_f$ if (k_0, ϵ_0) is in the Region I. This occurs because epsilon is proportional to k on the nullcline, while epsilon is proportional to k^{C_2} on the solution orbit and $C_2 > 1$. We can also conclude $k_0 > k_f$ and $\epsilon_0 > \epsilon_f$ if (k_0, ϵ_0) is in the Region II. Second, we should emphasize that k and epsilon increase (decrease) with increasing time in the Region I (II), since $\partial k / \partial t$ and $\partial \epsilon / \partial t$ are positive (negative). Therefore, if (k_0, ϵ_0) is in the Region I (II), the solution moves to the upper right (lower left), and is absorbed into the nullcline with the limit $t \rightarrow \infty$. We can conclude that the nullcline is a line attractor, not a repeller. The steady stable solution is given by $(k, \epsilon) = (k_f, \epsilon_f)$.

Note that k and epsilon vanish with the limit $t \rightarrow \infty$ for usual isotropic turbulent flow, even though the solution orbit for such flow is the same as one obtained here. Actually, the usual turbulent flow is described by the limit $K \rightarrow \infty$ in the present model. The nullcline is k axis in such a case, and the Region I vanishes. Therefore, all the solutions are absorbed into the origin. The finite K enables the turbulence to be survive with $t \rightarrow \infty$ for the homogeneous state.

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