

Shape-memory polymer microvalves and its application to a field-programmable valve array

Hiroaki Takehara^{1,2}, Koichiro Uto³, Mitsuhiro Ebara³, Takao Aoyagi³ and Takanori Ichiki¹

¹ School of Engineering, The University of Tokyo, JAPAN

² Research Fellow of the Japan Society for the Promotion of Science, JAPAN

³ Biomaterials Unit, National Institute for Materials Science (NIMS), JAPAN

2-11-16, Yayoi, Bunkyo-ku, Tokyo, 113-8656, Japan

Phone/FAX: +81-03-5841-7781, E-mail: h-takehara@bionano.t.u-tokyo.ac.jp

1. Introduction

Although extensive research has been conducted on microvalve technologies [1,2], the development of a simple and robust microvalve remains a challenging issue. In this paper, we report a microvalve that is actuated by the shape recovery of an SMP. An SMP is a material that can temporarily memorize shapes but reverts to its permanent shape upon exposure to an external stimulus such as heat. Compared with well-known metallic shape-memory alloys, SMPs show large deformability and changes in the elastic modulus at their response temperature, which are highly advantageous for the simple design and reliable actuation of microvalves.

2. Device principle

Figure 1 shows the proposed SMP microvalve. Poly(epsilon-caprolactone) (PCL) was used as the SMP. PCL can memorize the shape of microstructures at the submicrometer level [3] and reverts to its original shape near 50°C.

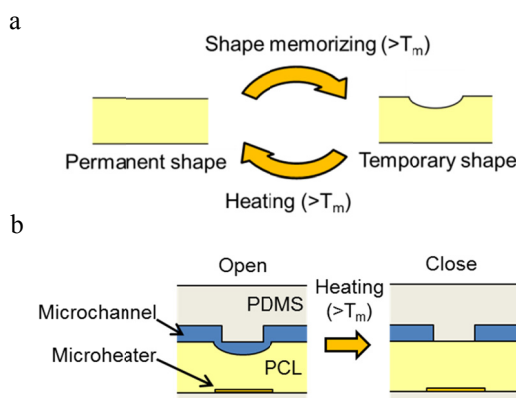


Fig. 1. (a) Schematic of an SMP. (b) Schematic of proposed SMP microvalve (N/O valve). An N/O valve has a concave shape as its temporary shape and a flat shape as its permanent shape. Valve actuation was controlled by heating using a microheater.

3. Results and discussion

Valve actuation was inspected by vertical imaging (Figure 2). Each valve operated at an electrical potential of 5 V applied to a microheater on a chip. As shown in Figure 3, each valve actuated within 150 ms when sufficient heat (>13.5 mJ) was applied.

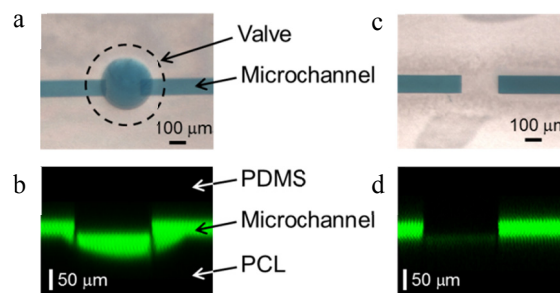


Fig. 2. (a) Optical micrograph of a SMP microvalve in the open state. (b) Vertical image of (a). Fluid can flow through the concave shape of the PCL layer. (c) Optical micrograph of a valve in the closed state. (d) Vertical image of (c). The concave shape of PCL recovered to a flat shape.

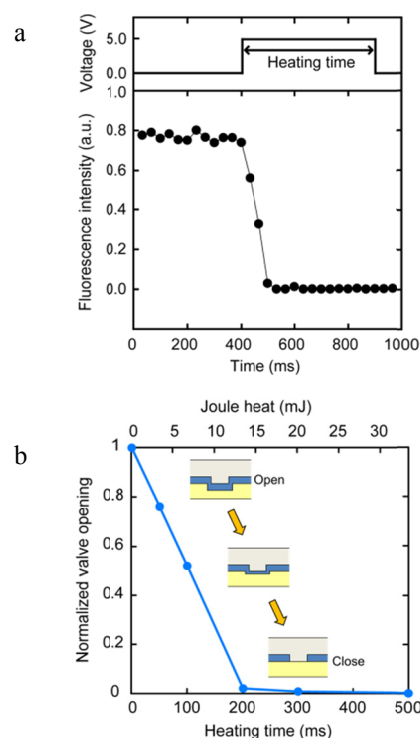


Fig. 3. (a) Time response of a SMP microvalve. Heating time is the duration of applying a voltage to a microheater. Valve opening was measured by determining fluorescence. The square area between the adjacent microchannels was monitored. The valve actuated within 150 ms. (b) Valve opening vs heating time and Joule heat. The valve can actuate upon the application of a sufficient amount of heat (>13.5 mJ).

Figure 4 shows N/O and N/C valves arranged in tandem. An N/O valve has a concave shape as its temporary shape and a flat shape as its permanent shape, and vice versa for an N/C valve. Tandemly arranged valves can actuate in sequence from a closed state to an open state and finally to a closed state. This sequence is one of the most frequently used sequences for performing the batch processing of liquid samples on a chip.

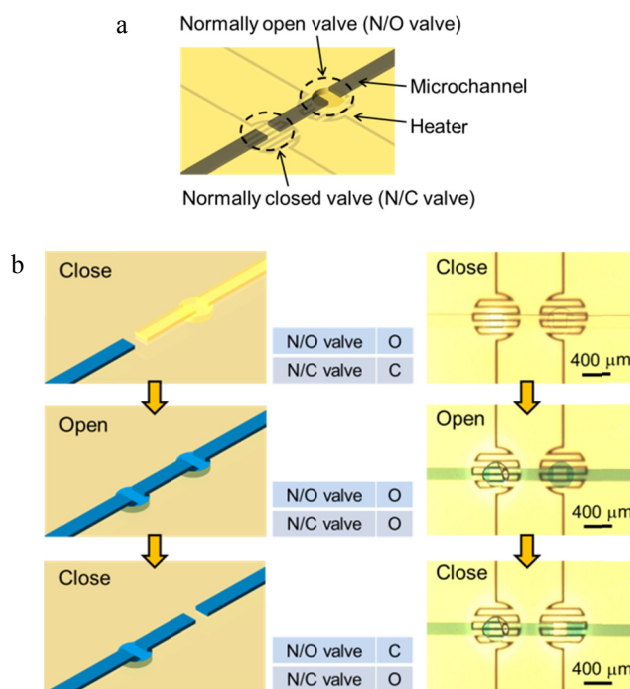


Fig. 4. (a) Schematic of N/O and N/C valves arranged in tandem. An N/O valve has a concave shape as its temporary shape and a flat shape as its permanent shape. An N/C valve has a flat shape as its temporary shape and a concave shape as its permanent shape. (b) Tandemly arranged N/O and N/C valves can actuate in sequence from a closed state to an open state and finally to a closed state.

Finally, we fabricated a FPVA as shown in Figure 5 and 6. This FPVA is analogous to a FPGA, which is a programmable integrated circuit that interconnects several logic modules [4]. In contrast, the FPVA has a microchannel network that interconnects microfluidic components such as chambers, mixers and sensors. Valves are arranged at each crossing point of the microchannel network. Selective valve actuation enables the on-demand formation of an arbitrary microfluidic network.

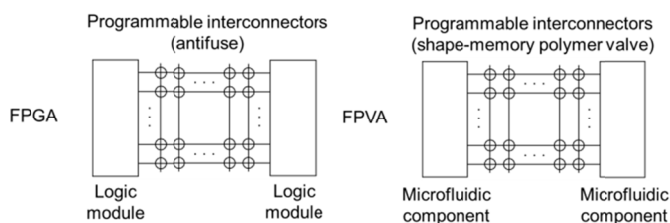


Fig. 5. Schematic architecture of FPGA and FPVA.

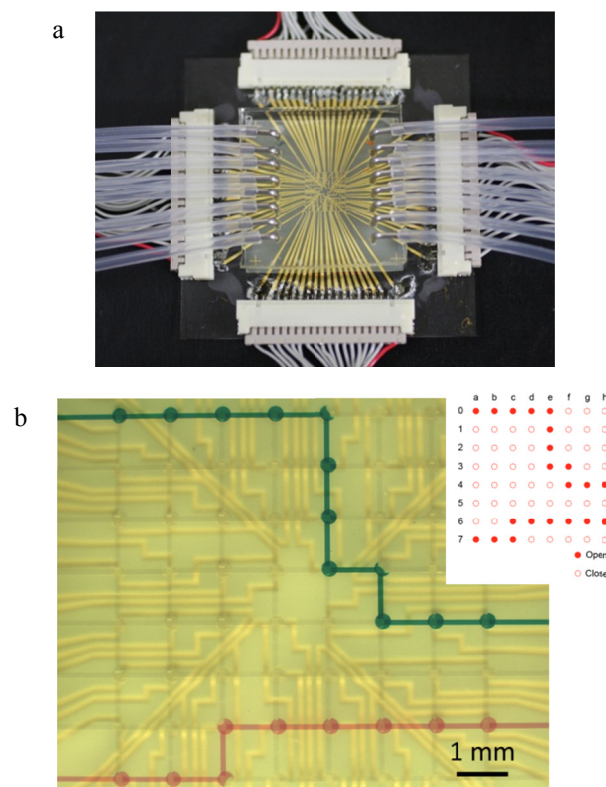


Fig. 6. (a) Optical micrograph of the FPVA device. (b) Optical photograph of programmed microchannel networks and schematic of programmed valve opening and closing (8×8=64 valves). Selected valves were closed, and the designed blue and red fluid lines were successfully observed.

4. Conclusions

We developed a novel SMP microvalve that can operate as either N/O or N/C valves and fabricated an FPVA with 8×8=64 valves to demonstrate the suitability for integration into a microfluidic network. The simple valve design and applicability of low-cost fabrication technology such as plastic molding and circuit printing are advantageous for use in disposable chips. Also, the electronically controllable feature is expected to be useful for realizing full-scale micro-TAS devices.

Acknowledgements

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